



Karthik Dantu

Research category: Systems, and Interdisciplinary

Research area: Robot perception, Multi-robot coordination, Mobile Systems

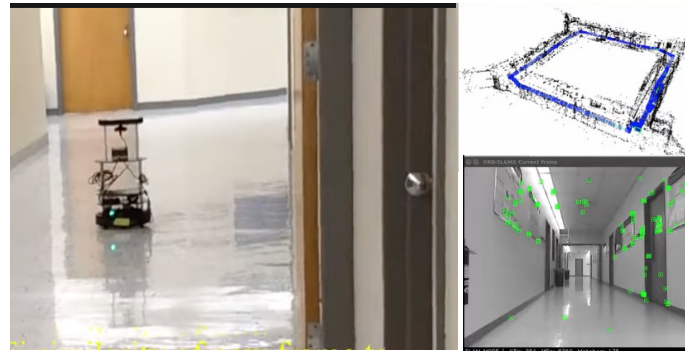
Research application: Infrastructure inspection, Mixed reality, autonomous racing, swarm robotics

Selected research projects:

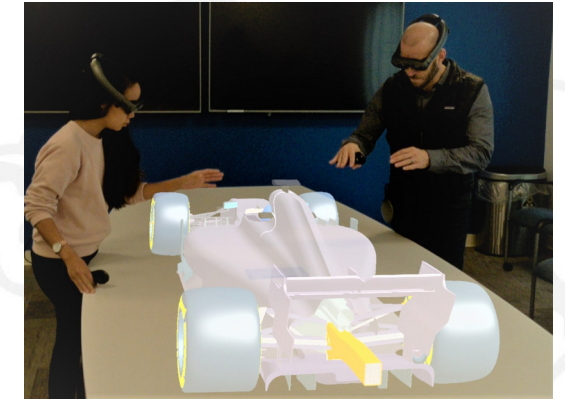
NSF CAREER Enabling Seamless Vision Sensing in Cloud-Edge Systems

AFOSR DURIP REASONS: RESilient, Adaptive, Scalable, autOnomy in Networked Swarms

A Robot Perception



B Mixed Reality Systems



C Timeliness and Correctness Challenges in Mobile Systems

