

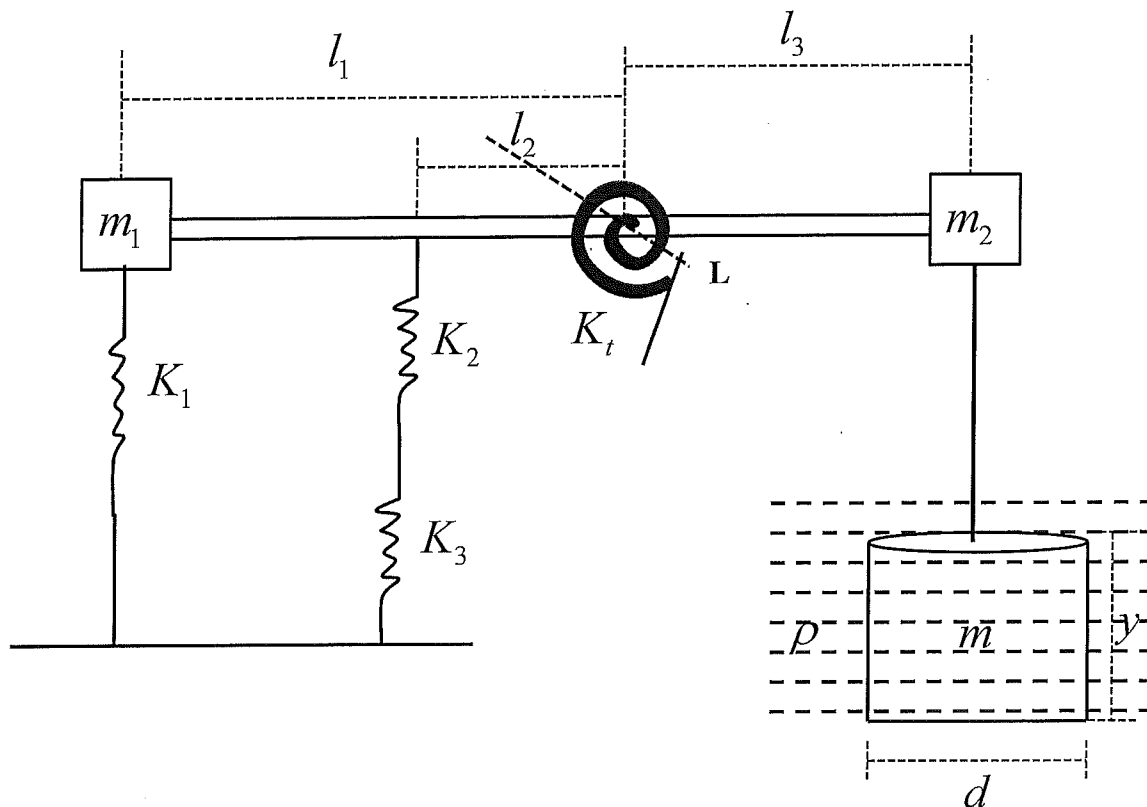
Department of Mechanical and Aerospace Engineering
2008 Ph.D Qualifying Exam
Jan 28, 2008
Dynamics and Control

Assigned # _____

NO TEXTBOOKS OR NOTES ALLOWED. YOU ARE REQUIRED TO ANSWER 4 OF THE 6 QUESTIONS.

Problem A:

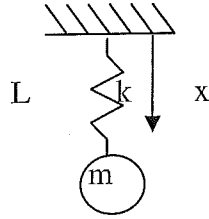
Derive the equation of motion of the system shown in the figure below.



What is the damping ratio and the natural frequency of the system?

Problem B:

Consider the spring mass system shown below. The spring has a mass density of δ kg/m in its un-deformed state, and an un-deformed length of L . Derive the equations of motion and determine the natural frequency of the system.



Problem C:

Consider the following partitioned system matrix:

$$A = \begin{bmatrix} A_{11}(t) & A_{12}(t) \\ 0 & A_{22}(t) \end{bmatrix}$$

where $A_{11}(t)$, $A_{22}(t)$ and $A_{12}(t)$ are generally time-varying sub-matrices (they cannot be assumed to be scalars).

a) Prove that the state transition matrix has the form

$$\Phi(t, t_0) = \begin{bmatrix} \Phi_{11}(t, t_0) & \Phi_{12}(t, t_0) \\ 0 & \Phi_{22}(t, t_0) \end{bmatrix}$$

where $(\partial / \partial t) \Phi_{ii}(t, t_0) = A_{ii}(t) \Phi_{ii}(t, t_0)$, $i = 1, 2$ and

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b) Use this result to find $\Phi(t, 0)$ for

$$A = \begin{bmatrix} -1 & e^{2t} \\ 0 & -1 \end{bmatrix}$$

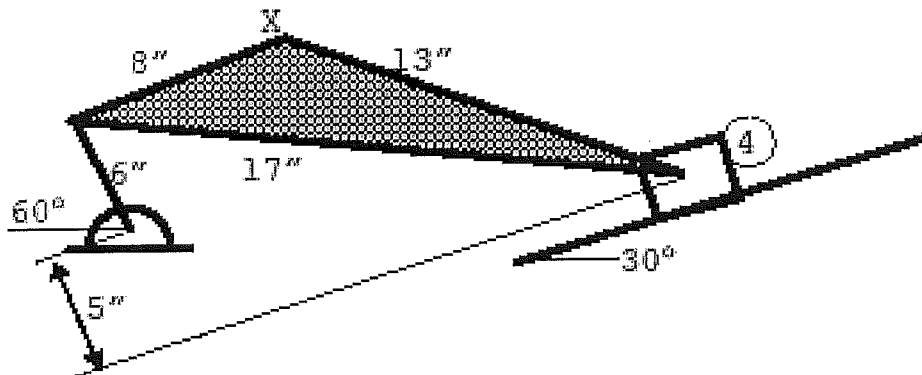
Prove that your answer is correct.

Problem D:

Consider the four-link mechanism shown in the figure below.
Determine the maximum displacement of link 4.

The mechanism is driven by a D.C. motor attached to the crank with an angular velocity of 60 rpm clockwise.

Determine the velocity of the link 4 when the crank rotates at 60 rpm for the link locations shown below.

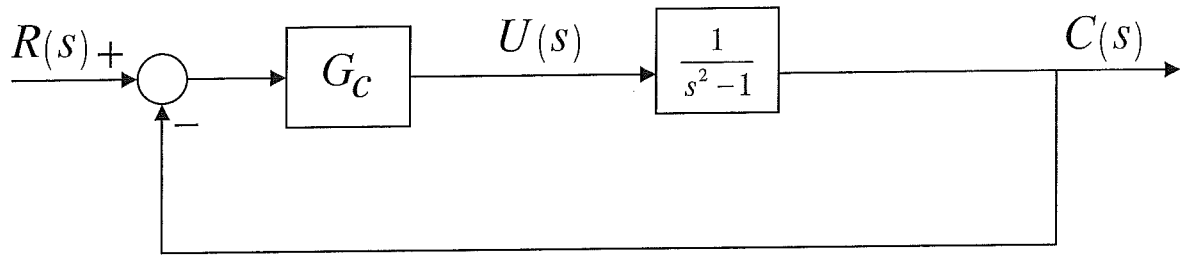


Problem E:

Consider the following open-loop system:

$$\frac{C(s)}{U(s)} = \frac{1}{s^2 - 1}$$

- With an impulse input for $u(t)$ and zero initial conditions, solve for $c(t)$.
- Draw the Bode plot for the open-loop system.
- Suppose we multiply the open-loop transfer function by a constant. What does this do to the magnitude and phase of the Bode plot?
- Can the system be controlled from an asymptotic sense using proportional control only? Explain this answer using 1) a phase margin argument, as well as 2) from the closed-loop transfer.
- Design a compensator G_c to stabilize the system so that the closed-loop system has a natural frequency of 2 rad/sec and a damping ratio of $\sqrt{2}/2$.



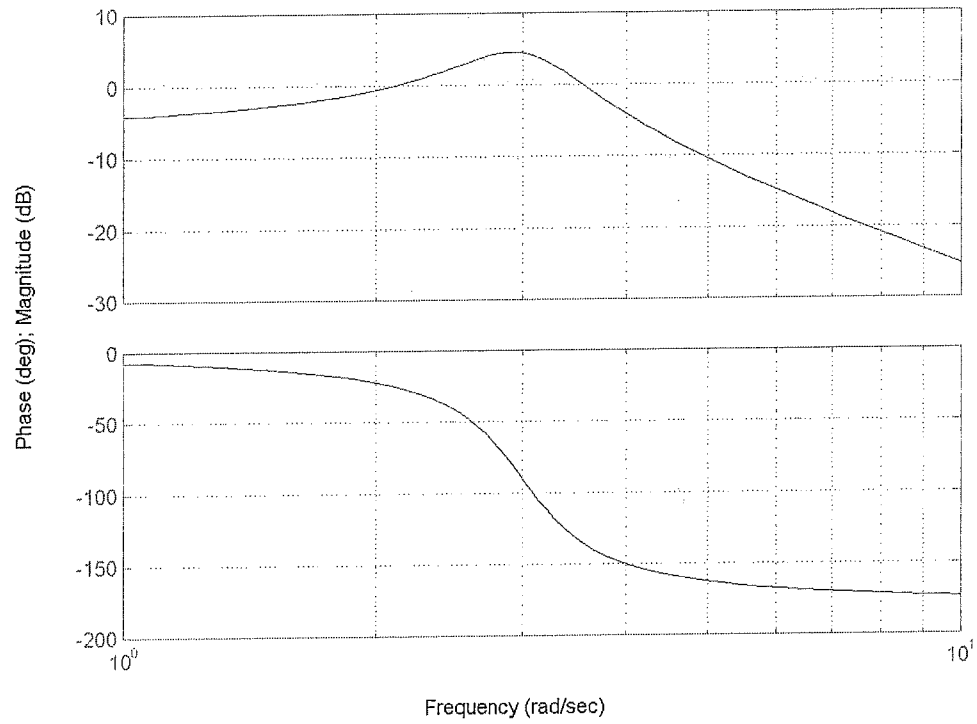
Problem F:

A linear, time-invariant, SISO (single input – single output) system is represented by the Bode plots shown below. Answer the following questions:

- Estimate the system's transfer function
- Is this system stable, marginally stable, or unstable? Explain.
- What is the system's output if the input is $u = 5 * \sin(4t)$?
- If the input is $u = 10 * \sin(w*t)$, for what value(s) of w (if any) is the system output magnitude exactly equal to 10?
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- If the input is $u = 10 * \sin(w*t)$, for what value of w does the greatest output magnitude occur?
- If the input is $u = 10 * \sin(w*t)$, for what value(s) of w (if any) does the system act as an amplifier?
- What is the system's approximate natural frequency (if any)?

What is the system's approximate damping ratio?

Bode Diagrams



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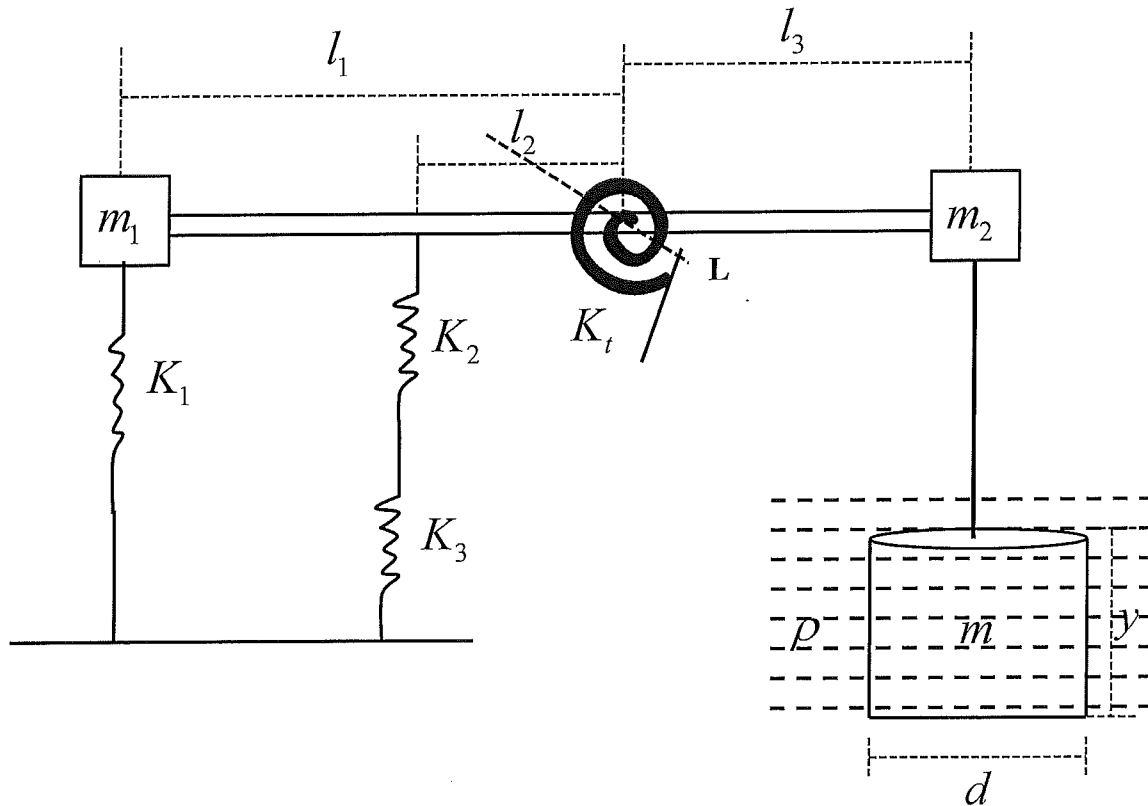
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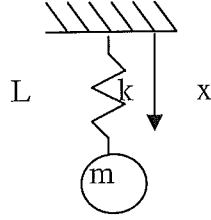
Derive the equation of motion of the system shown in the figure below.



What is the damping ratio and the natural frequency of the system?

Problem B:

Consider the spring mass system shown below. The spring has a mass density of δ kg/m in its un-deformed state, and an un-deformed length of L . Derive the equations of motion and determine the natural frequency of the system.



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Consider the following partitioned system matrix:

$$A = \begin{bmatrix} A_{11}(t) & A_{12}(t) \\ 0 & A_{22}(t) \end{bmatrix}$$

where $A_{11}(t)$, $A_{22}(t)$ and $A_{12}(t)$ are generally time-varying sub-matrices (they cannot be assumed to be scalars).

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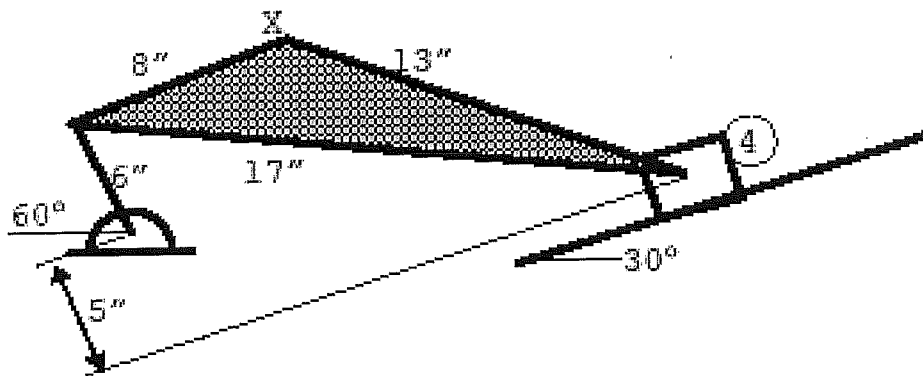
Prove that your answer is correct.

Problem D:

Consider the four-link mechanism shown in the figure below.
Determine the maximum displacement of link 4.

The mechanism is driven by a D.C. motor attached to the crank with an angular velocity of 60 rpm clockwise.

Determine the velocity of the link 4 when the crank rotates at 60 rpm for the link locations shown below.

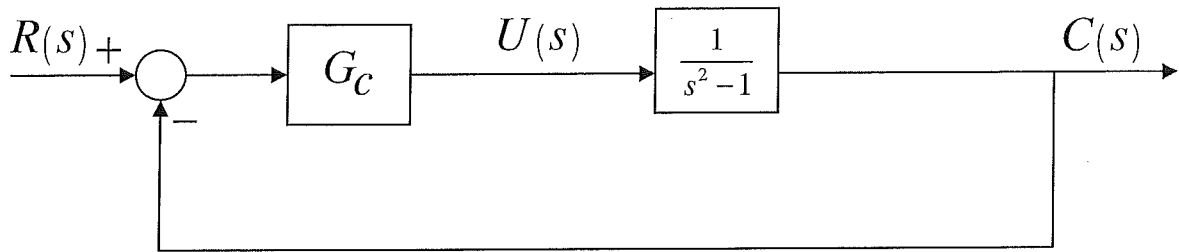


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Consider the following open-loop system:

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- With an impulse input for $u(t)$ and zero initial conditions, solve for $c(t)$.
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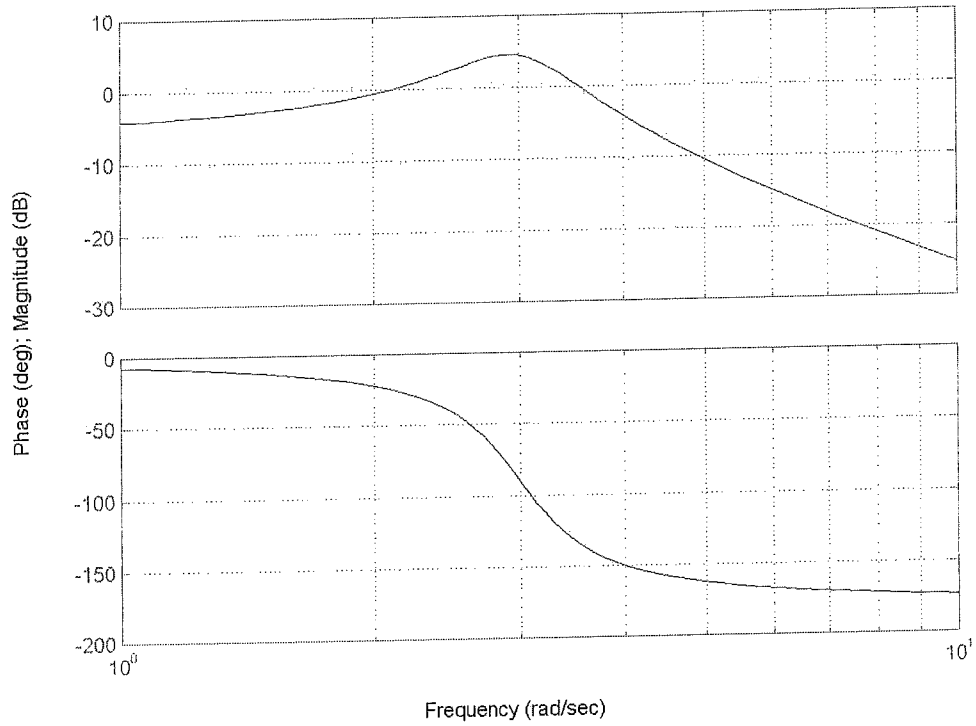
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A linear, time-invariant, SISO (single input – single output) system is represented by the Bode plots shown below. Answer the following questions:

- a) Estimate the system's transfer function
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- c) What is the system's output if the input is $u = 5 * \sin(4t)$?
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- j) What is the system's approximate natural frequency (if any)?

What is the system's approximate damping ratio?

Bode Diagrams



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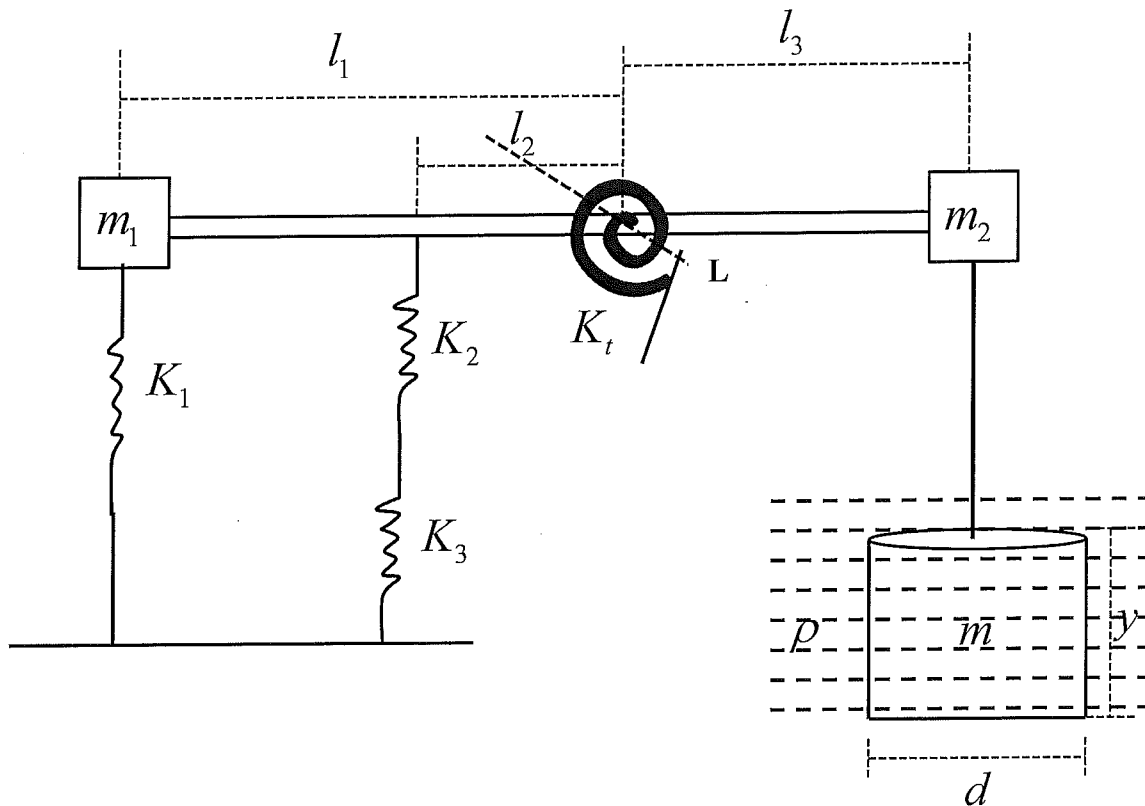
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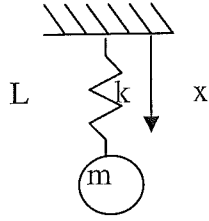
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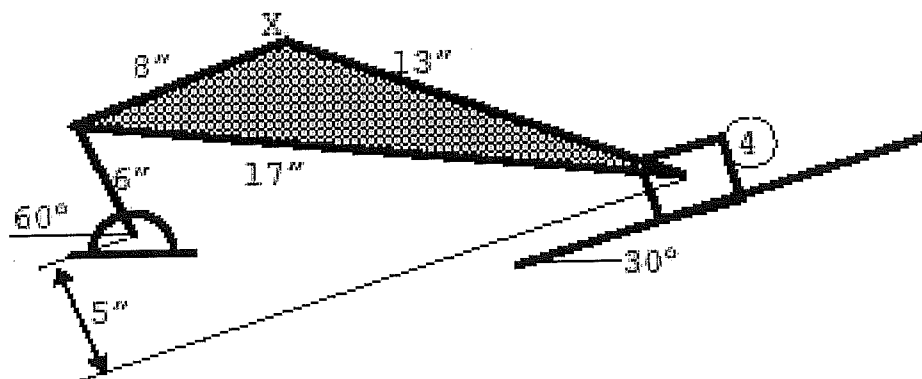
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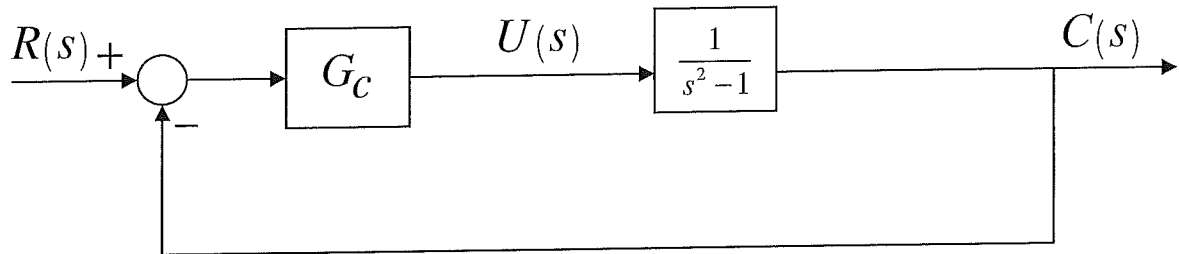


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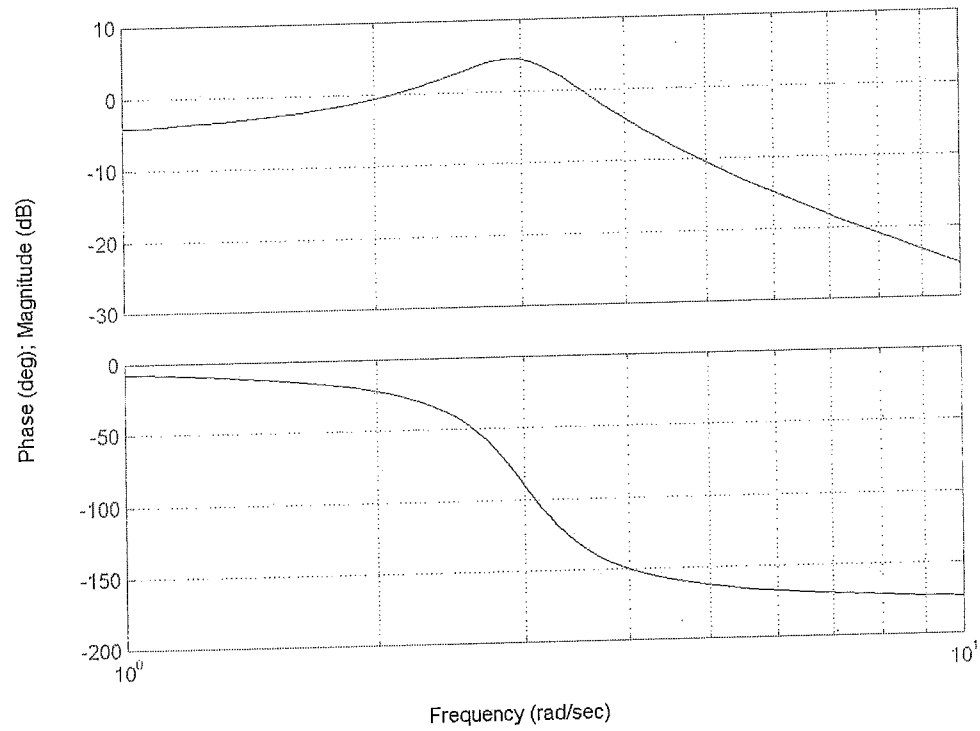
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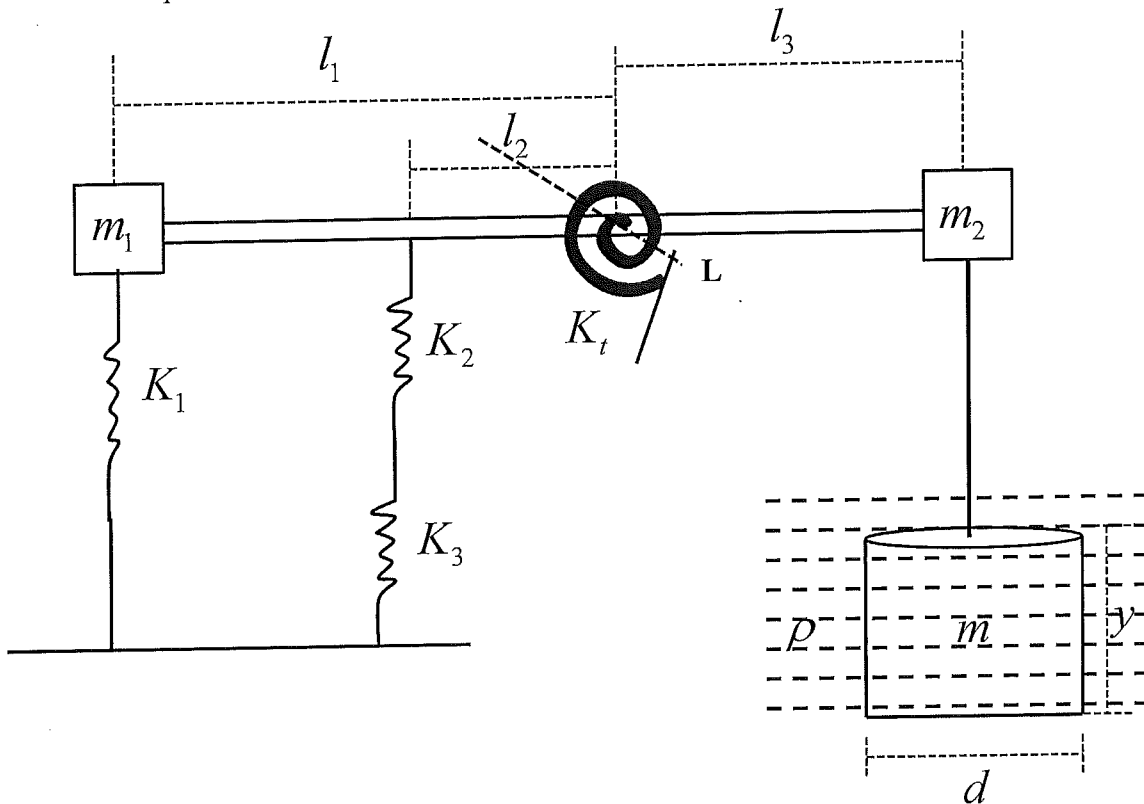
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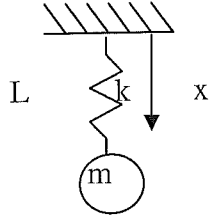
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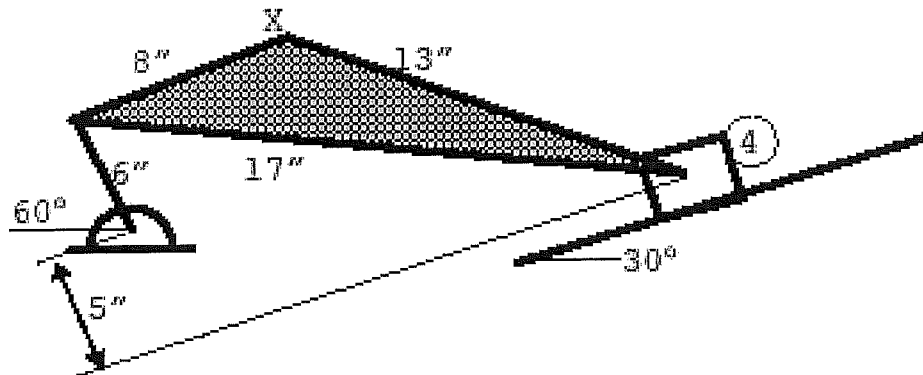
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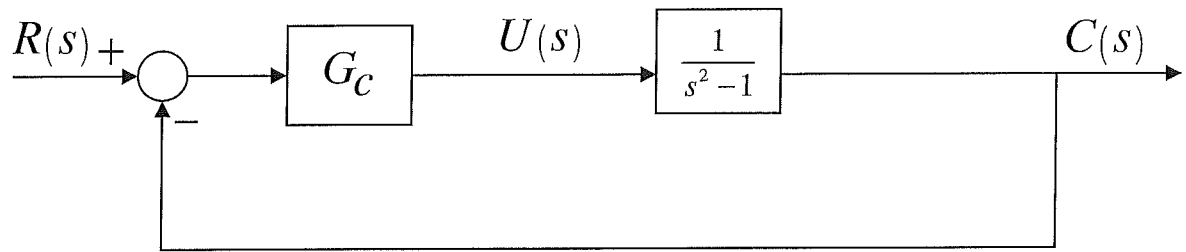


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